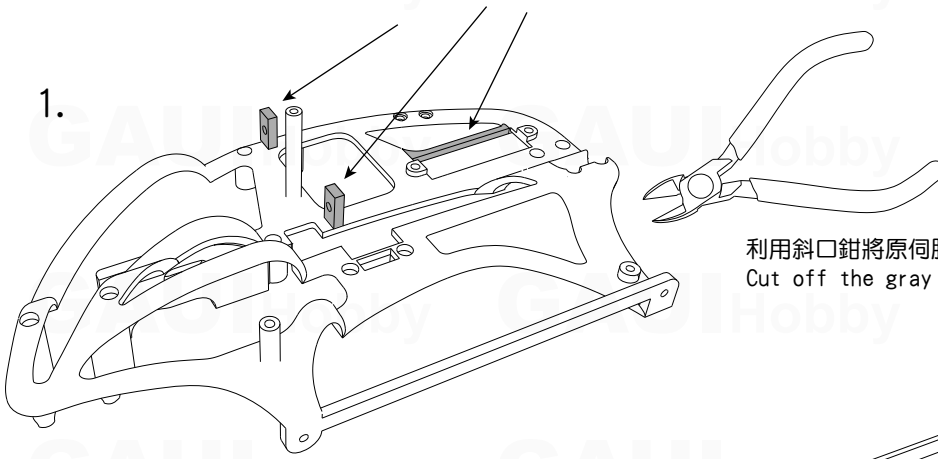
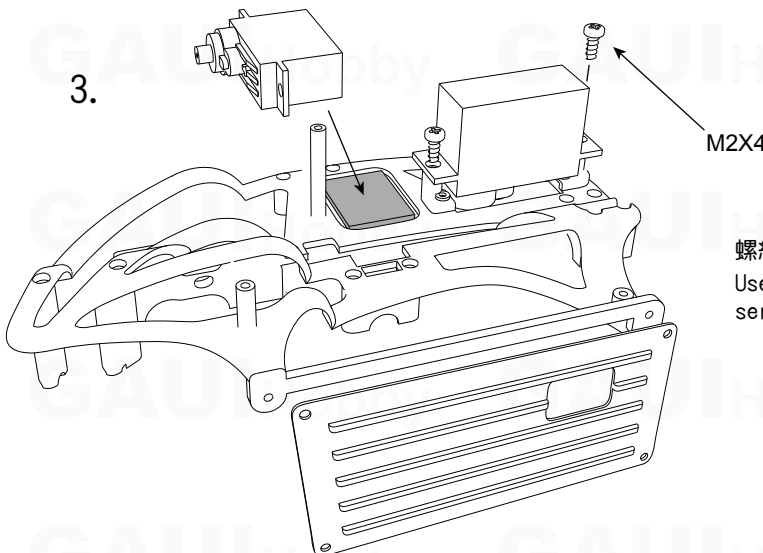
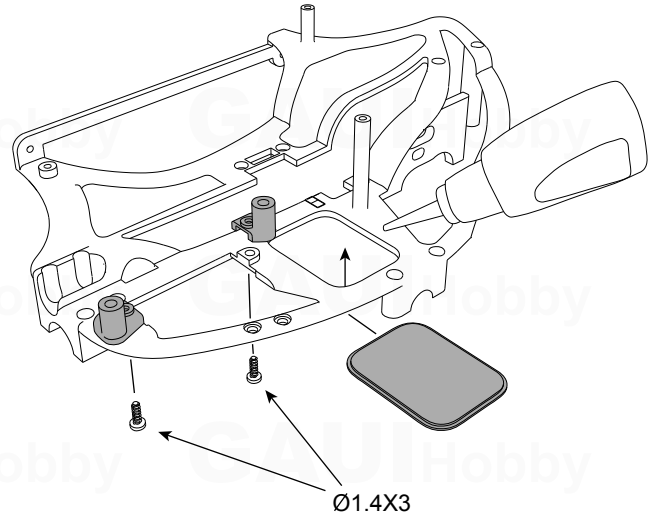


BMS-306 servo 組裝說明
BMS-306 servo Installation



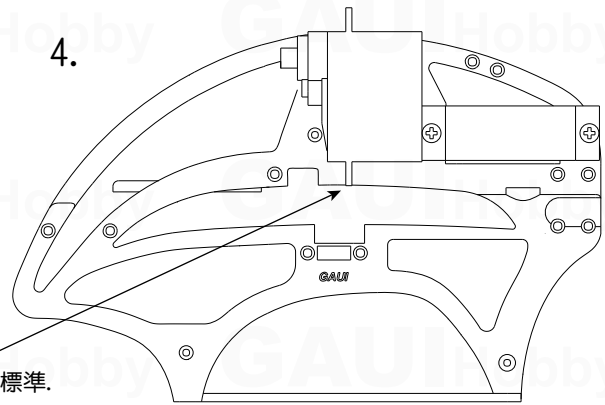
利用斜口鉗將原伺服機座(左,右)及後橫桿剪掉。
Cut off the gray area as shown on figure.

2. 如圖將後伺服機的轉接座鎖上(再以瞬間膠固定最好),
前伺服機座則由內部置入,再以瞬間膠由外部固定(左右皆同)。
Tighten the servo joints onto both frames and use CA
to adhere them. Install the front servo plate from the
inner side of frame and use CA to adhere it as shown.



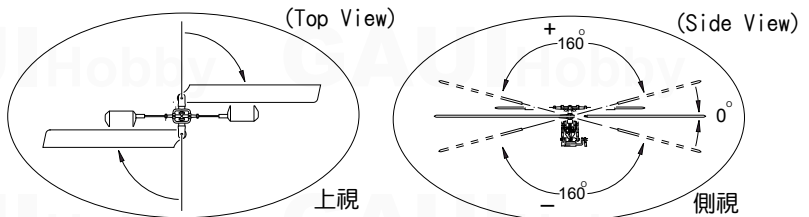
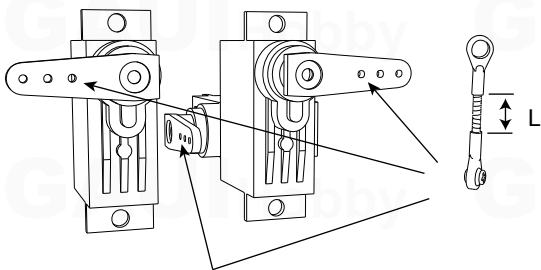
將平台固定在機身與腳架之間。
Attach the bottom plate onto
the position as shown.

前伺服機(左右皆同)利用雙面膠固定在機身,後伺服機則以
螺絲固定。(相對位置如圖4.)
Use the double-side adhesive tape to adhere the front
servo and tighten the rear servo as shown in fig.4.



以切齊不突出為標準。
Align with the edge.

5.



檢視螺距的方式: 如圖將旋翼收起, 利用透明量角器檢視旋翼變化
若為右圖160度時, 代表此時螺距為(180-160)/2=10度。

Pitch degrees : If the angle of the figure above is 160 degrees, it
indicates the pitch is (180-160)/2=10 degrees.

將伺服機連接到接收機後開啟電源, 在發射機搖桿為中立時(pitch=50%)將舵角片裝上並成垂直(如圖), 將拉桿固定在第一孔
此時旋翼螺距應為0度(前兩支拉桿L約4mm, 後方L約16mm, 若螺桿太長可修短)。

Wiring the servos to the receiver and turn on the power of Tx and Rx, install the servo horns onto servos
with correct angle (The control stick of throttle should be in middle position and the pitch curve is 50%).
Install the linkages and balls onto the position as shown. (The " L" of the front servo linkage is 4mm approx.
and the " L" of the rear servo linkage is 16mm approx. Shorten the rod by cutting it partially if it is
too long to fit.)